DEEP LEARNING

Lecture 11: Generative Models

Dr. Yang Lu

Department of Computer Science and Technology

luyang@xmu.edu.cn





Image Translation

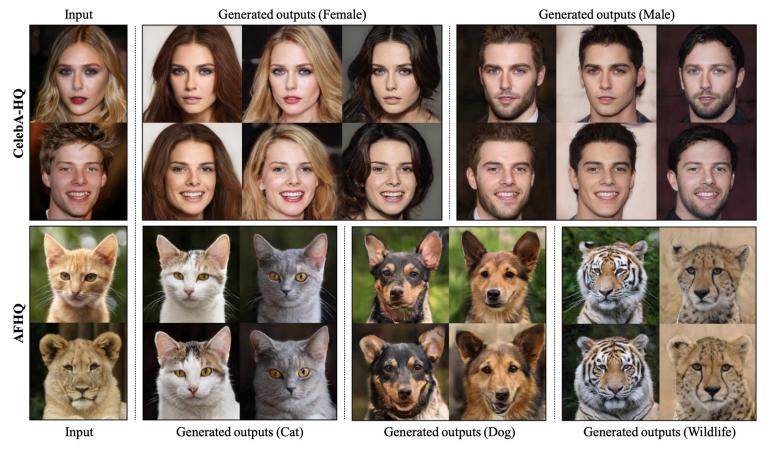




Image Translation





Scene Generation





Facial Attribute Manipulation

Input Synthesized expressions







Facial Attribute Manipulation





Gaze Correction

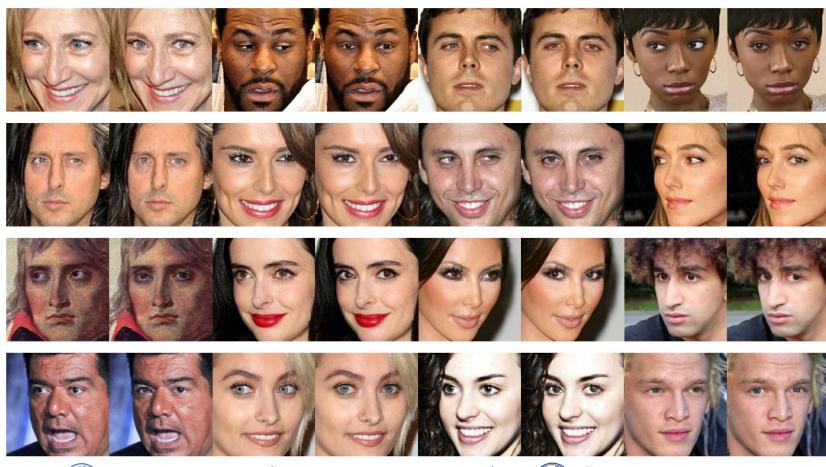


Image Animation



























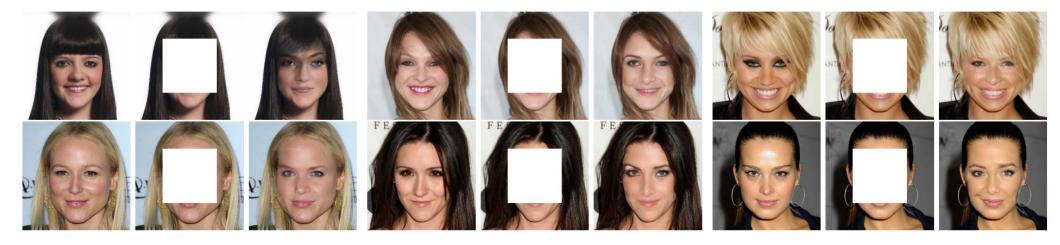








Image Inpainting







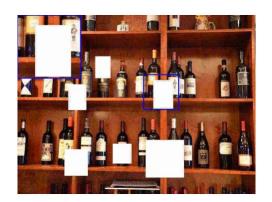
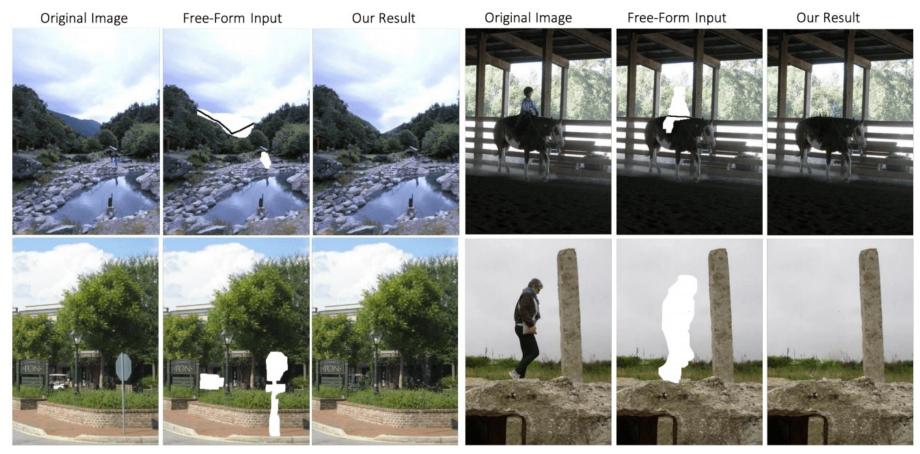








Image Inpainting



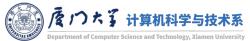


Image Blending

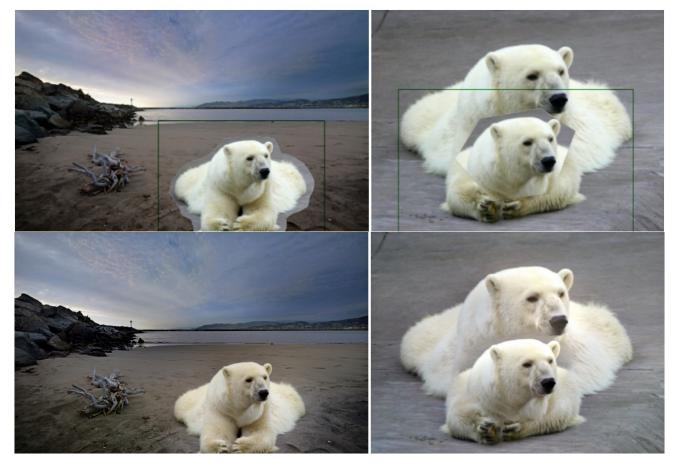
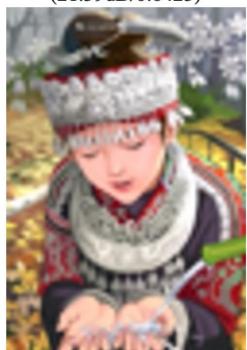




Image Super-Resolution

ORIGINAL RESULT

bicubic (21.59dB/0.6423)



SRResNet (23.53dB/0.7832)



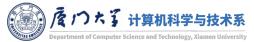
SRGAN (21.15dB/0.6868)



original







Makeup





Text-to-image generation



"a hedgehog using a calculator"



"a corgi wearing a red bowtie and a purple party hat"



"robots meditating in a vipassana retreat"



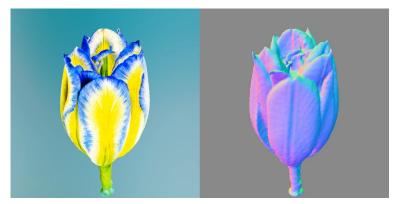
"a fall landscape with a small cottage next to a lake"



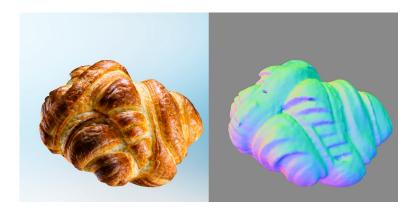
Video generation

Text2Video-Zero:
Text-to-Image Diffusion Models are
Zero-Shot Video Generators

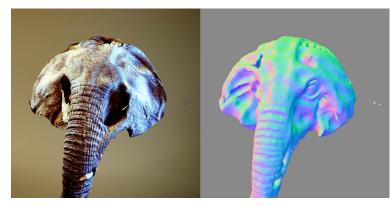
Text-to-3D generation



A blue tulip



A delicious croissant



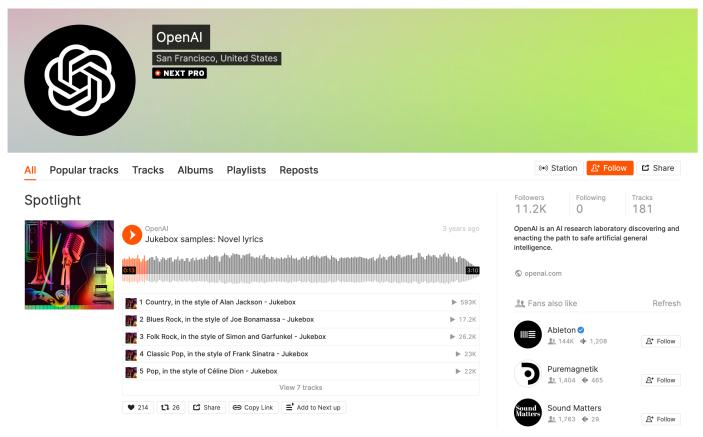
An elephant skull



Michelangelo style statue of dog reading news on a cellphone



Music Generation



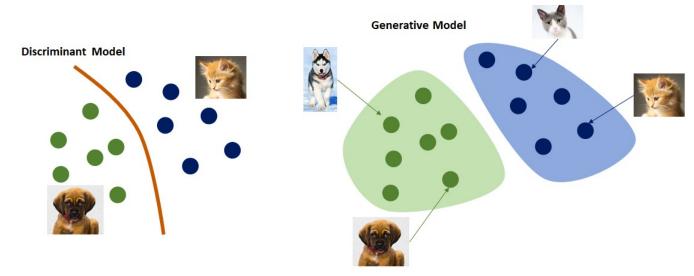
Generated music samples: https://soundcloud.com/openai audio





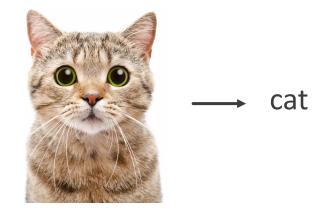
Generative vs. Discriminative

- In machine learning, two main approaches are called the generative approaches and the discriminative approaches.
- Given an observable variable X and a target variable Y:
 - A generative model is a statistical model of the data distribution P(X) or the joint probability distribution on $X \times Y$: P(X,Y).
 - A discriminative model is a model of the conditional distribution of Y given X: P(Y|X=x).



Discriminative Approaches

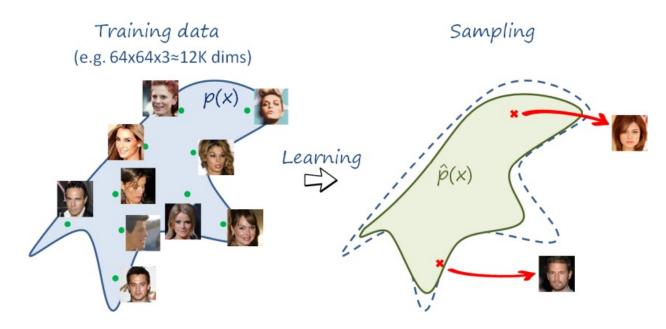
- Most supervised learning methods fall into discriminative approaches.
 - Given data: (x, y), x is data, y is label.
 - Goal: Learn a function to map $x \to y$, namely posterior probability P(Y|X=x).
 - Examples: Classification, regression, object detection, face recognition, sentiment classification, etc.



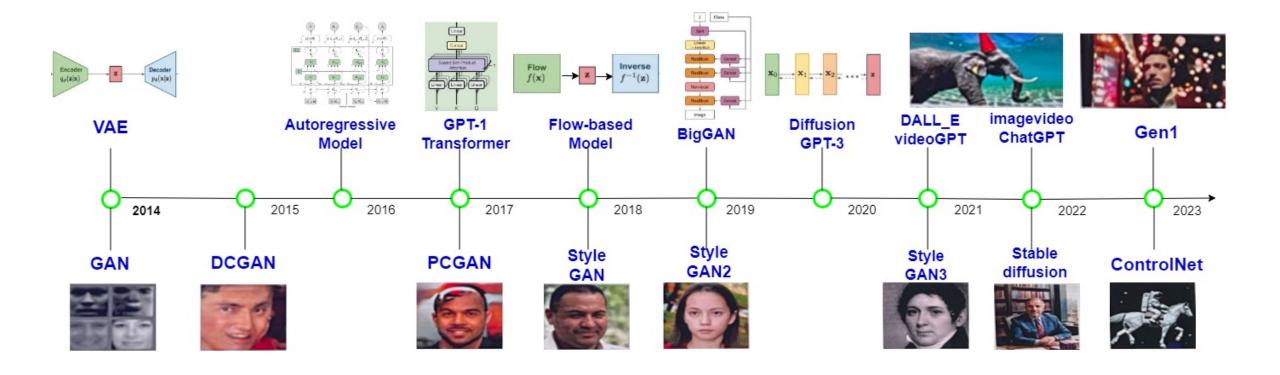


Generative Approaches

- Given training data, generate new samples from same distribution.
- Objectives:
- 1. Learn $p_{model}(x)$ that approximates $p_{data}(x)$.
- 2. Sample a new x from $p_{model}(x)$.



Generative Models





Outlines

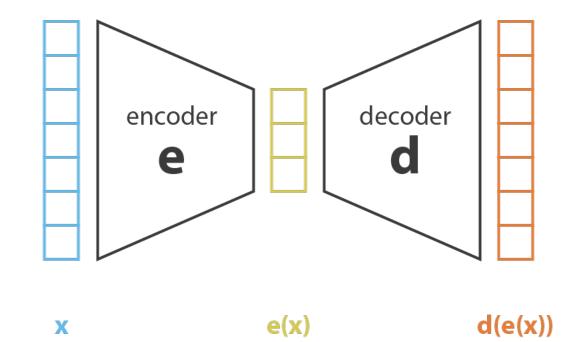
- Variational Autoencoder
- Generative Adversarial Nets
- Diffusion Model



VARIATIONAL AUTOENCODER

Autoencoder

in space Rⁿ



x = d(e(x)) lossless encoding
no information is lost
when reducing the
number of dimensions

initial data encoded data encoded-decoded data

in latent space R^m (with m<n)

back in the initial space Rⁿ

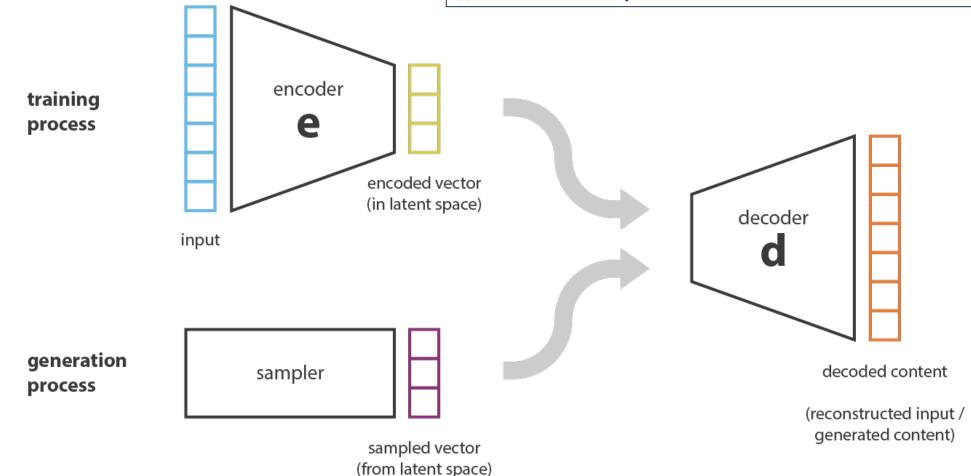
loss =
$$||\mathbf{x} - \hat{\mathbf{x}}||^2 = ||\mathbf{x} - \mathbf{d}(\mathbf{z})||^2 = ||\mathbf{x} - \mathbf{d}(\mathbf{e}(\mathbf{x}))||^2$$

Auto-encoding variational bayes

DP Kingma, M Welling - arXiv preprint arXiv:1312.6114, 2013 - arxiv.org

... **variational** lower bound yields a simple differentiable unbiased estimator of the lower bound; this SGVB (Stochastic Gradient **Variational Bayes**..., we propose the **AutoEncoding** VB (AEVB...

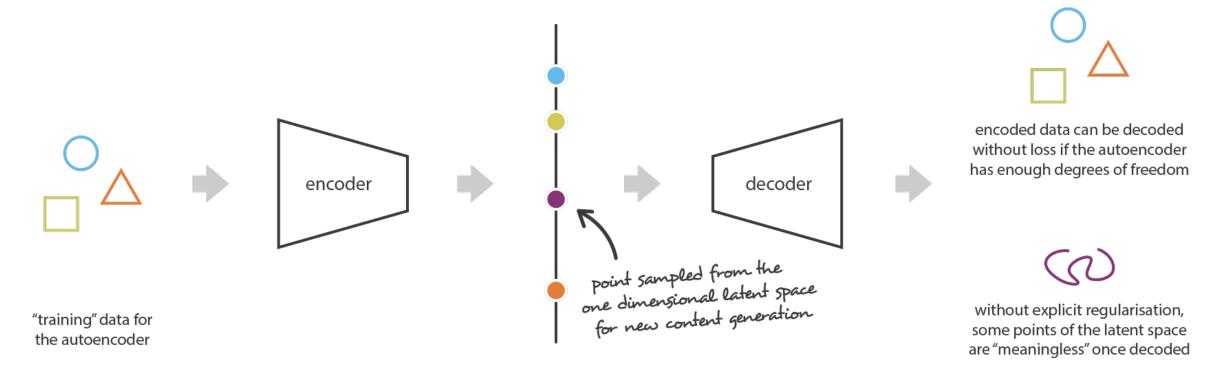
☆ Save ⑰ Cite Cited by 30917 Related articles All 44 versions ♦







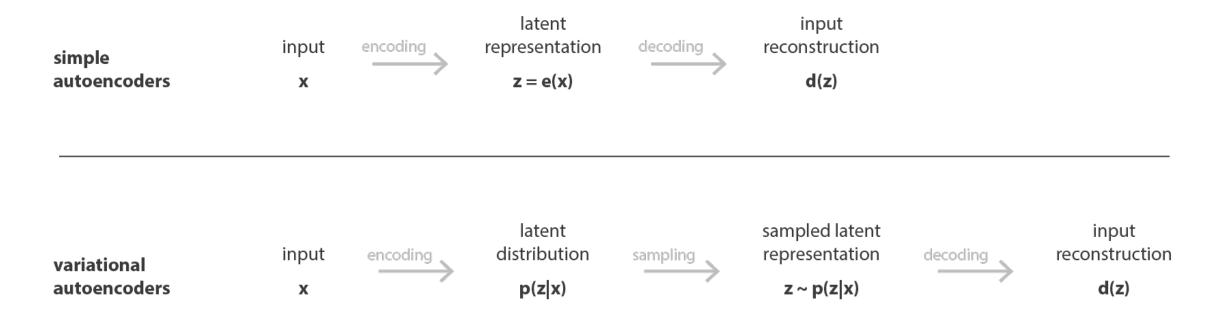
■ The autoencoder is solely trained to encode and decode with as few loss as possible, no matter how the latent space is organized.



- •A variational autoencoder can be defined as being an autoencoder whose training is:
 - regularized to avoid overfitting;
 - ensure that the latent space has good properties that enable generative process.

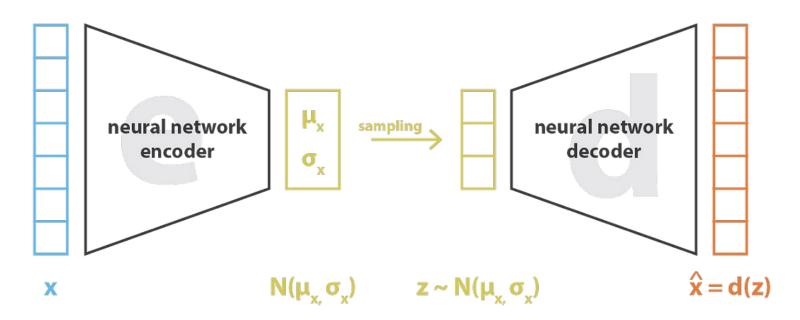


•Instead of encoding an input as a single point, we encode it as a distribution over the latent space.





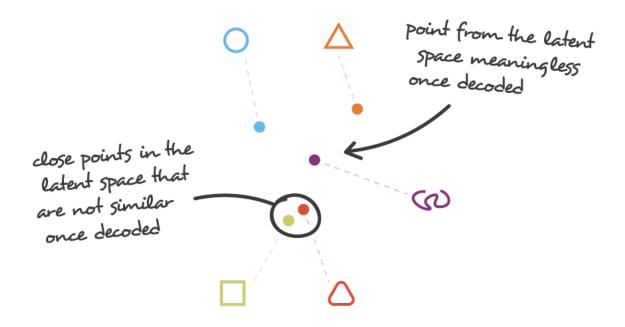
Regularize the organization of the latent space by making the distributions returned by the encoder close to a standard normal distribution.



loss =
$$|| x - x^2 ||^2 + KL[N(\mu_x, \sigma_x), N(0, I)] = || x - d(z)||^2 + KL[N(\mu_x, \sigma_x), N(0, I)]$$

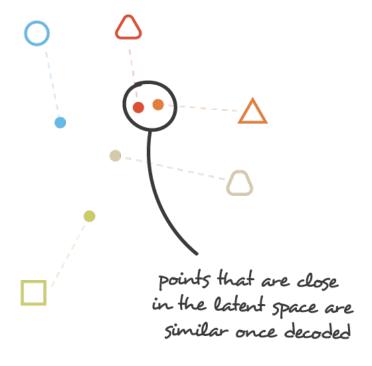






irregular latent space







regular latent space

- The loss of the autoencoder is to minimize both:
 - the reconstruction loss (how similar the autoencoder's output to its input);
 - the latent loss (how close its hidden nodes were to a normal distribution).
- It doesn't guarantee the quality of the generated image. A major drawback of VAEs is the blurry outputs that they generate. VAE models tend to produce unrealistic, blurry samples.



Human faces generated by VAEs



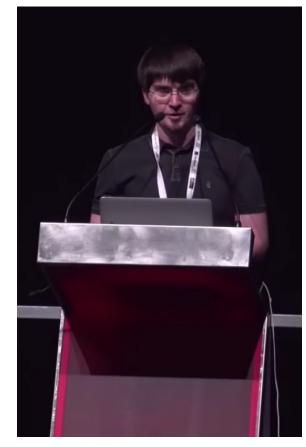
GAN

GAN

Generative adversarial nets

I Goodfellow, J Pouget-Abadie... - Advances in neural ..., 2014 - proceedings.neurips.cc ... We propose a new framework for estimating **generative** models via **adversarial nets**, in which we simultaneously train two models: a **generative** model G that captures the data ... ☆ Save ೨೨ Cite Cited by 61677 Related articles All 61 versions ≫

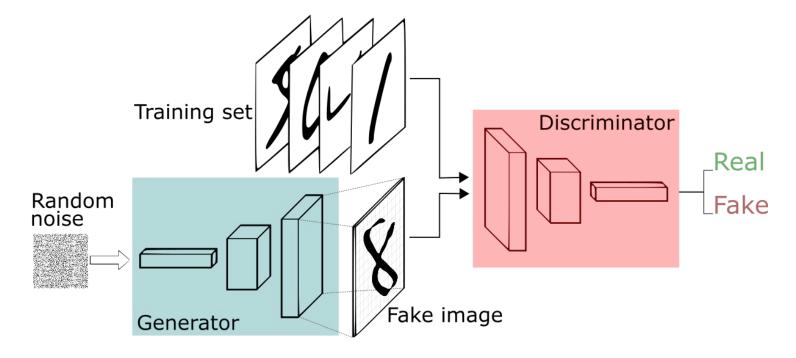
- •GAN was proposed by Ian Goodfellow in 2014.
- Yann LeCun described GANs as "the most interesting idea in the last 10 years in machine learning".
- Ian presented and explained his paper in NIPS 2016 with a 2-hour presentation.



lan in NIPS 2016

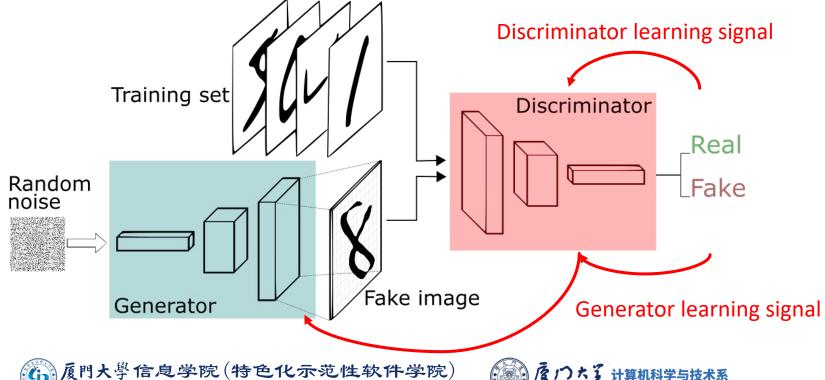
GAN: How to Do

- GAN is composed by a generator and a discriminator. They are both neural networks.
 - Generator network: try to fool the discriminator by generating real-looking images.
 - Discriminator network: try to distinguish between real and fake images.



GAN: How to Do

- Generator and discriminator tells each other where it was wrong.
 - Generator tells discriminator how I fool you.
 - Discriminator tells generator how I detect you.





GAN: How to Learn

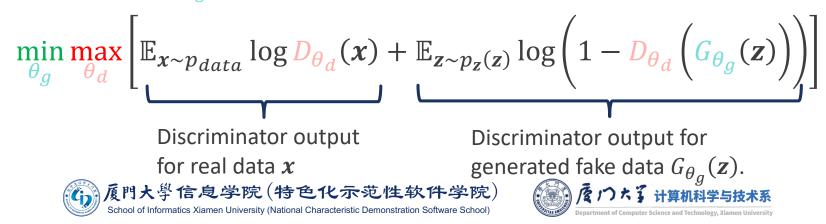
- Given a prior on input noise variables $z \sim p_z(z)$, generator $G_{\theta_g}(z)$ take z as input and map it into data space.
- Discriminator $D_{\theta_d}(x)$ takes the data $x \sim p_{data}$ as input and output probability that x came from the real data rather than generated data $G_{\theta_q}(z)$.
- $\blacksquare D_{\theta_d}$ and G_{θ_g} have different goals (1 for real, 0 for fake):
 - Generator wants: $D_{\theta_d}\left(G_{\theta_g}(\mathbf{z})\right) \rightarrow 1$.
 - Discriminator wants: $D_{\theta_d}(x) \to 1$, $D_{\theta_d}(G_{\theta_g}(z)) \to 0$.





GAN: How to Learn

- By maximizing the log-likelihood, the overall objective is to simultaneously train over all x with random generated z:
 - train G_{θ_g} to minimize $\log \left(1 D_{\theta_d} \left(G_{\theta_g}(\mathbf{z})\right)\right)$;
 - train D_{θ_d} to maximize $\log D_{\theta_d}(x)$ and $\log \left(1 D_{\theta_d}\left(G_{\theta_g}(z)\right)\right)$.
- In other words, D_{θ_d} and G_{θ_g} play the following two-player minimax game:



GAN: How to Learn

Objective:

$$\min_{\theta_g} \max_{\theta_d} \left[\mathbb{E}_{\boldsymbol{x} \sim p_{data}} \log D_{\theta_d}(\boldsymbol{x}) + \mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{z}}(\boldsymbol{z})} \log \left(1 - D_{\theta_d} \left(G_{\theta_g}(\boldsymbol{z}) \right) \right) \right]$$

Alternate between:

Gradient ascent on discriminator:

$$\max_{\theta_d} \left[\mathbb{E}_{\boldsymbol{x} \sim p_{data}} \log D_{\theta_d}(\boldsymbol{x}) + \mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{z}}(\boldsymbol{z})} \log \left(1 - D_{\theta_d} \left(G_{\theta_g}(\boldsymbol{z}) \right) \right) \right]$$

Gradient descent on generator:

$$\min_{\theta_g} \left[\mathbb{E}_{\mathbf{z} \sim p_{\mathbf{z}}(\mathbf{z})} \log \left(1 - D_{\theta_d} \left(G_{\theta_g}(\mathbf{z}) \right) \right) \right]$$

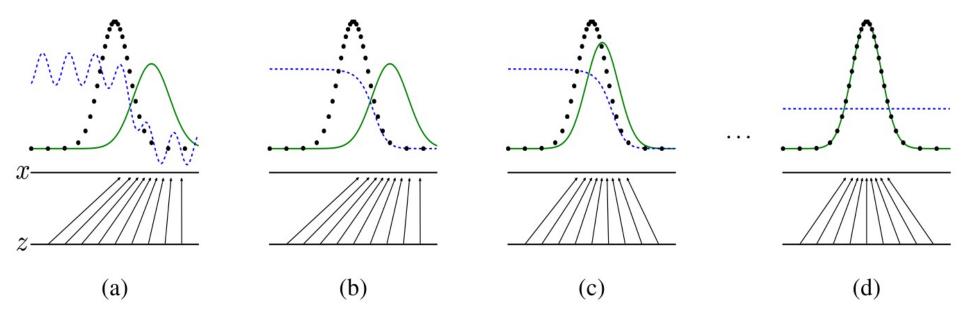


GAN: How to Learn

- After several steps of training, if G and D have enough capacity, they will reach a point at which both cannot improve because $p_g=p_{data}$.
 - Generator can generate real image.
 - Discriminator is unable to differentiate between the two distributions, i.e. $D_{\theta_d}(x) = 1/2$.

discriminative distribution

data distribution generative distribution





GAN: Algorithm

Algorithm 1 Minibatch stochastic gradient descent training of generative adversarial nets. The number of steps to apply to the discriminator, k, is a hyperparameter. We used k = 1, the least expensive option, in our experiments.

for number of training iterations do

for k steps do

- Sample minibatch of m noise samples $\{z^{(1)}, \ldots, z^{(m)}\}$ from noise prior $p_q(z)$.
- Sample minibatch of m examples $\{x^{(1)}, \dots, x^{(m)}\}$ from data generating distribution $p_{\text{data}}(x)$.
- Update the discriminator by ascending its stochastic gradient:

$$\nabla_{\theta_d} \frac{1}{m} \sum_{i=1}^m \left[\log D\left(\boldsymbol{x}^{(i)}\right) + \log\left(1 - D\left(G\left(\boldsymbol{z}^{(i)}\right)\right)\right) \right].$$

end for

- Sample minibatch of m noise samples $\{z^{(1)}, \dots, z^{(m)}\}$ from noise prior $p_g(z)$.
- Update the generator by descending its stochastic gradient:

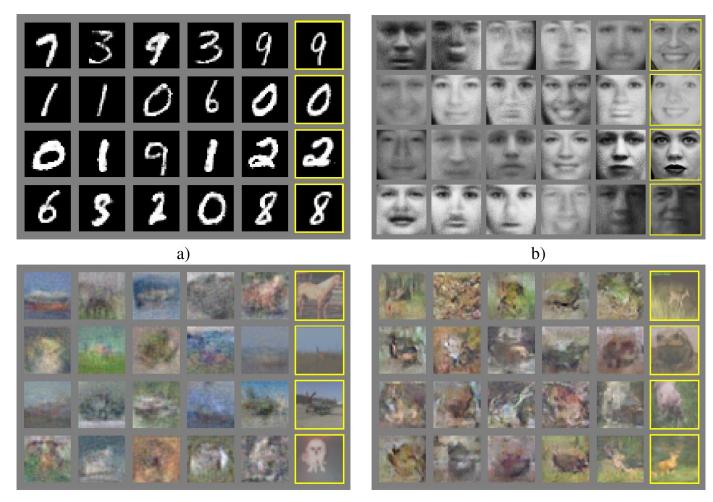
$$\nabla_{\theta_g} \frac{1}{m} \sum_{i=1}^{m} \log \left(1 - D\left(G\left(\boldsymbol{z}^{(i)}\right) \right) \right).$$

end for

The gradient-based updates can use any standard gradient-based learning rule. We used momentum in our experiments.



GAN: Result

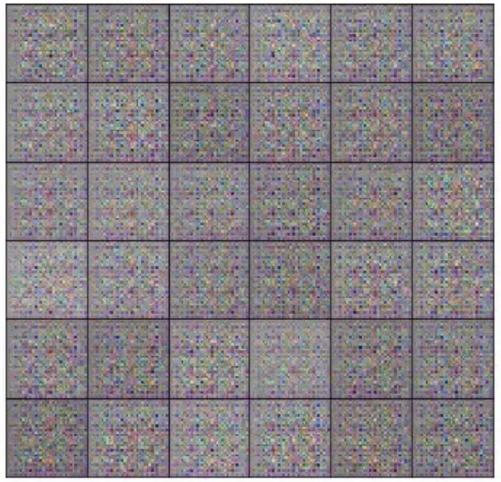


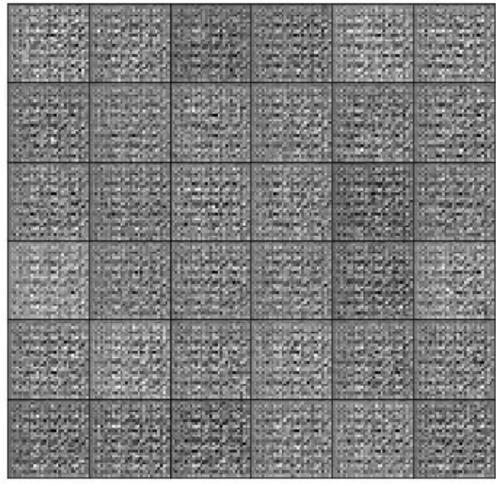
Rightmost column shows the nearest training example of the neighboring sample, in order to demonstrate that the model has not memorized the training set.





GAN: Result





SVHNs

GAN Starts an Era





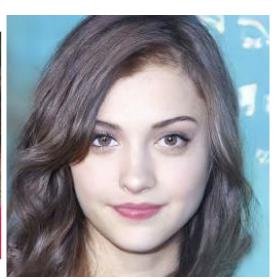


2016



2017





2020



2023

DCGAN

Unsupervised representation learning with deep convolutional generative adversarial networks

A Radford, L Metz, S Chintala - arXiv preprint arXiv:1511.06434, 2015 - arxiv.org

... REPRESENTATION LEARNING FROM UNLABELED DATA Unsupervised representation learning ... A classic approach to unsupervised representation learning is to do clustering on the ... \Leftrightarrow Save 59 Cite Cited by 16206 Related articles All 5 versions \Rightarrow

- Vanilla GAN simply uses MLP, rather than CNN in both generator and discriminator.
- CNN can be easily applied to discriminator.
- Now the problem is: how can CNN be used as a generator?
 - Pooling leads to downsampling, how to upsampling?



Filter: 3×3

Input: 2×2

1	2
3	4



10	20	30
40	50	60
30	20	10



10	20	30	
40	50	60	
30	20	10	



Filter: 3×3

Input: 2×2

1	2
3	4



10	20	30
40	50	60
30	20	10



10	20+	30+	60
	20	40	0
40	50+	60+	120
40	80	100	120
30	20+	10+	20
30	60	40	20



Filter: 3×3

Input: 2×2

1	2
3	4



10	20	30
40	50	60
30	20	10

Output: 4×4

10	40	70	60
40+	130	160	120
30	+60	+90	120
30+	80+	50+	20
120	150	180	20
90	60	30	



Filter: 3×3

Input: 2×2

1	2
3	4



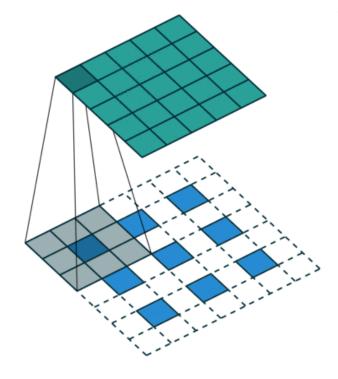
10	20	30
40	50	60
30	20	10



10	40	70	60
70	190	250	120+
70	+40	+80	120
150	230+	230+	20+
130	160	200	240
90	60+	30+	40
90	120	80	40

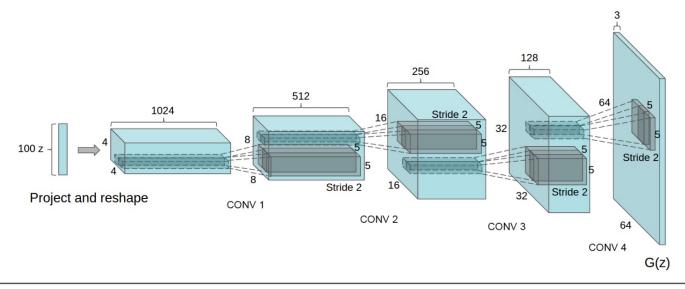


- Fractionally-strided convolutions are also called transposed convolutions.
 - PyTorch: torch.nn.ConvTranspose2d.
 - TensorFlow: tf.keras.layers.Conv2DTranspose.
- Some researchers are used to call deconvolutions. However, true deconvolutions are the inverse operation of convolution, which is not the same as fractionally-strided convolutions.



Transposed convolution with stride is equivalent to convolving with zero-padding and inserting zeros.

DCGAN



Architecture guidelines for stable Deep Convolutional GANs

- Replace any pooling layers with strided convolutions (discriminator) and fractional-strided convolutions (generator).

 stride=2 everywhere
- Use batchnorm in both the generator and the discriminator.
- Remove fully connected hidden layers for deeper architectures.
- Use ReLU activation in generator for all layers except for the output, which uses Tanh.
- Use LeakyReLU activation in the discriminator for all layers.





DCGAN: Visual Results



The generated bedrooms look very nice (at that time)!

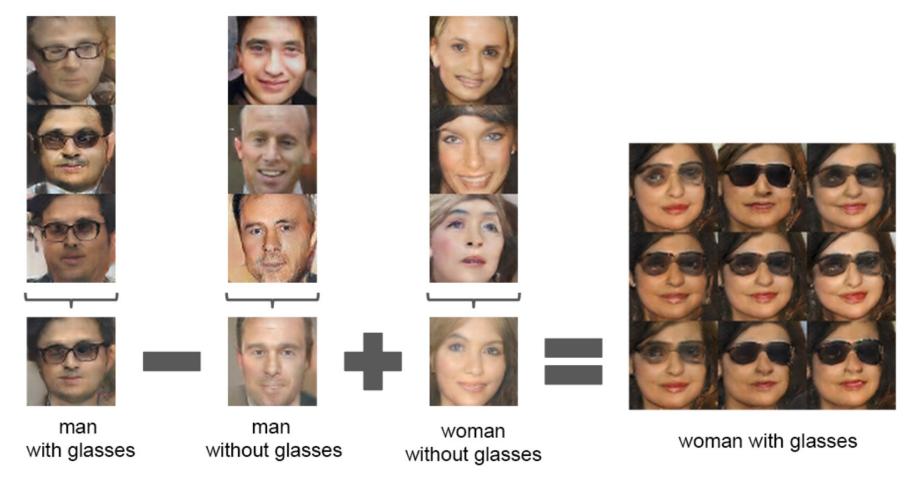
DCGAN: Walking in the Latent Space

• If walking in this latent space results in semantic changes to the image generations (such as objects being added and removed), we can reason that the model has learned relevant and interesting representations.



Interpolation between a series of 9 random points in Z show that the space learned has smooth transitions.

DCGAN: Vector Arithmetic



For each column, the Z vectors of samples are averaged. Arithmetic was then performed on the mean vectors creating a new vector Y.

DCGAN: Use as Feature Extractor

- Train on Imagenet-1k and then use the discriminator's convolutional features from all layers.
- Maxpooling each layers representation to produce a 4×4 spatial grid.
- These features are then flattened and concatenated to form a 28672 dimensional vector.
- A regularized linear L2-SVM classifier is trained on top of them.

Model	Accuracy	Accuracy (400 per class)	max # of features units
1 Layer K-means	80.6%	63.7% (±0.7%)	4800
3 Layer K-means Learned RF	82.0%	$70.7\%~(\pm 0.7\%)$	3200
View Invariant K-means	81.9%	$72.6\%~(\pm 0.7\%)$	6400
Exemplar CNN	84.3%	77.4% ($\pm 0.2\%$)	1024
DCGAN (ours) + L2-SVM	82.8%	73.8% (±0.4%)	512



Conditional generative adversarial nets

M Mirza, S Osindero - arXiv preprint arXiv:1411.1784, 2014 - arxiv.org

- ... way to train **generative** models. In this work we introduce the **conditional** version of **generative**
- ... We show that this model can generate MNIST digits conditioned on class labels. We also ...

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- We can't control what we generate from the vanilla GAN.
 - Noise is the only input and it is totally random.
- How can we tell GAN what we want it to generate?
- Straightforward solution: replace data distribution by conditional distribution.

$$p(x) \rightarrow p(x|y)$$
.

- Now, the problem becomes:
 - \blacksquare Generator: generate a sample for class y.
 - Discriminator: distinguish the real sample in class y and the generated sample in class y.



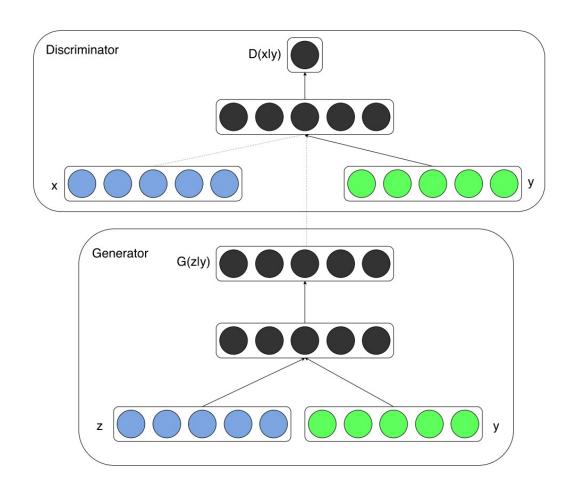


CGAN

Both generator and discriminator are conditioned on some extra information y:

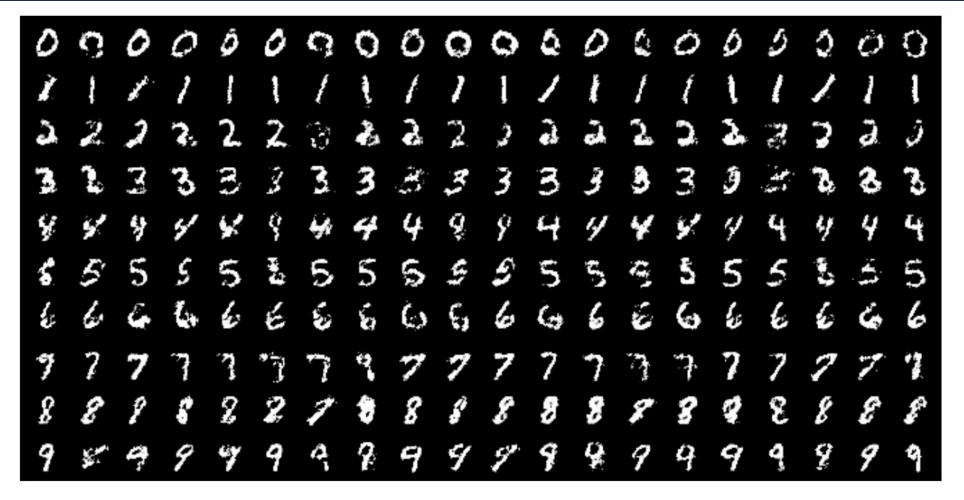
$$\min_{\theta_g} \max_{\theta_d} \left[\mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(\boldsymbol{x}|\boldsymbol{y}) + \mathbb{E}_{z \sim p(z)} \log \left(1 - D_{\theta_d} \left(G_{\theta_g}(\boldsymbol{z}|\boldsymbol{y}) \right) \right) \right].$$

- y could be any kind of auxiliary information, such as class labels or data from other modalities.
 - E.g. the speech of saying that class.





CGAN



Generate MNIST digits by directly feeding one-hot class label.





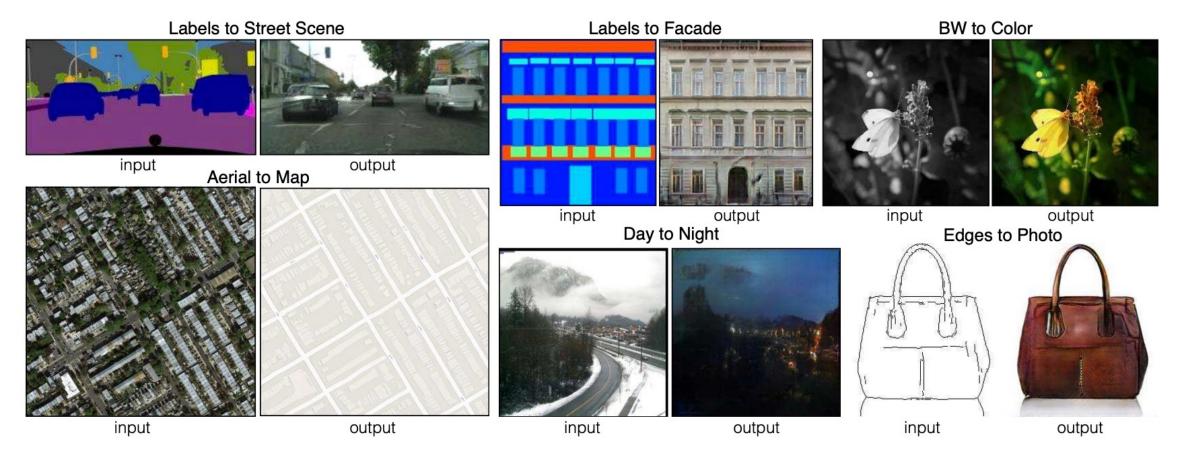
pix2pix

Image-to-image translation with conditional adversarial networks

P Isola, JY Zhu, T Zhou... - Proceedings of the IEEE ..., 2017 - openaccess.thecvf.com

- ... In analogy to automatic language translation, we define automatic **image-to-image** translation as the problem of translating one possible representation of a scene into another, given ...
- ☆ Save ワワ Cite Cited by 20433 Related articles All 24 versions ১৯

Given a pair of images, transfer the style of one image to another.

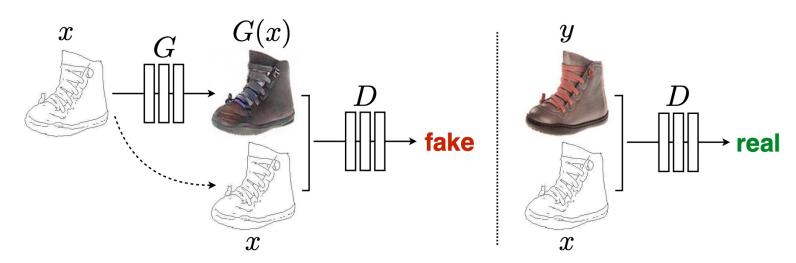




pix2pix

- The model is based on CGAN.
- As an improvement, the generator is tasked to not only fool the discriminator but also to be near the ground truth output.
- L_1 penalization is added to the loss of CGAN to encourage less blurring:

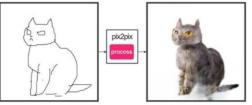
$$L_{L_1}(G) = \mathbb{E}_{x,y,z}[\|y - G(x,z)\|_1].$$



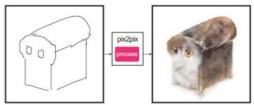


pix2pix: More Applications

#edges2cats by Christopher Hesse



by @gods_tail



by @ivymyt



by @vvid

$Sketch \rightarrow Portrait$



by Mario Klingemann

"Do as I do"



by Brannon Dorsey

${\bf Depth}{\rightarrow} {\bf Streetview}$



by Jasper van Loenen

Palette generation



by Jack Qiao

Background removal



by Kaihu Chen

Sketch \rightarrow Pokemon



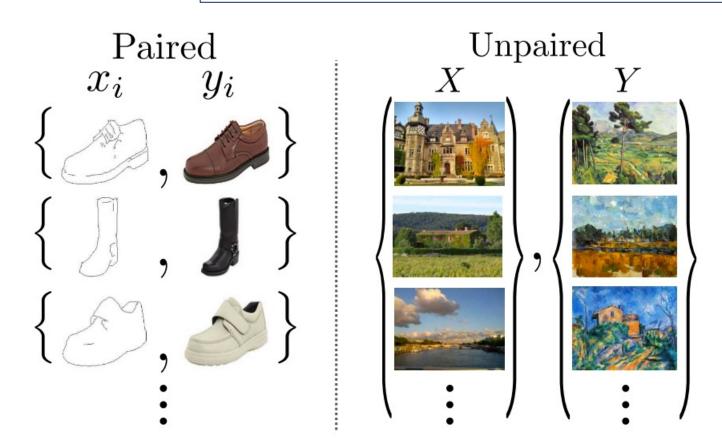
by Bertrand Gondouin

Unpaired image-to-image translation using cycle-consistent adversarial networks

JY Zhu, T Park, P Isola, AA Efros - Proceedings of the IEEE ..., 2017 - openaccess.thecvf.com

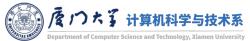
- ... losses on domains X and Y yields our full objective for **unpaired image-to-image** translation. ... We first compare our approach against recent methods for **unpaired image-to-image** ...
- ☆ Save ワワ Cite Cited by 20082 Related articles All 26 versions ≫

- Paired examples can be expensive to obtain.
- •Can we translate from X ↔ Y in an unsupervised manner?



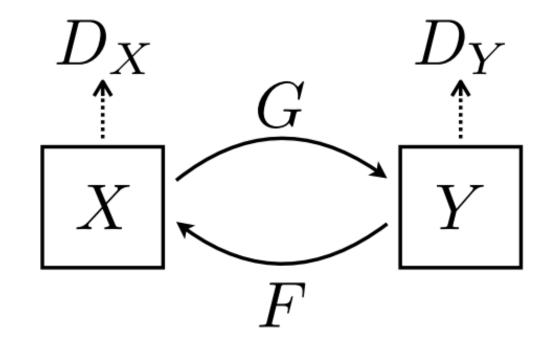
Paired vs. unpaired examples





Two generators:

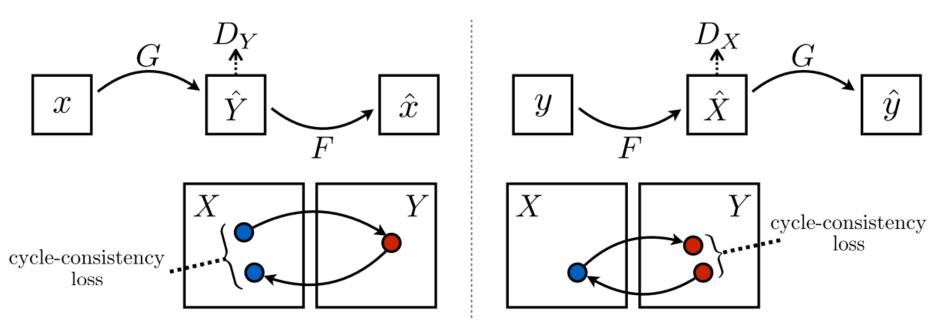
- $\blacksquare G: X \to Y;$
- $\blacksquare F \colon Y \to X.$
- Two discriminators:
 - D_X aims to distinguish between images $\{x\}$ and translated images $\{F(y)\}$;
 - D_Y aims to discriminate between $\{y\}$ and $\{G(x)\}$.





- If we can go from X to \widehat{Y} via G, then it should also be possible to go from \widehat{Y} back to X via F.
- Cycle consistency loss is added to the original adversarial loss:

$$L_{\text{cyc}}(G,F) = \mathbb{E}_{x} \left[\left\| F(G(x)) - x \right\|_{1} \right] + \mathbb{E}_{y} \left[\left\| G(F(x)) - y \right\|_{1} \right].$$





Monet C Photos

Monet \longrightarrow photo

photo → Monet

Photograph

Failed case:





Monet



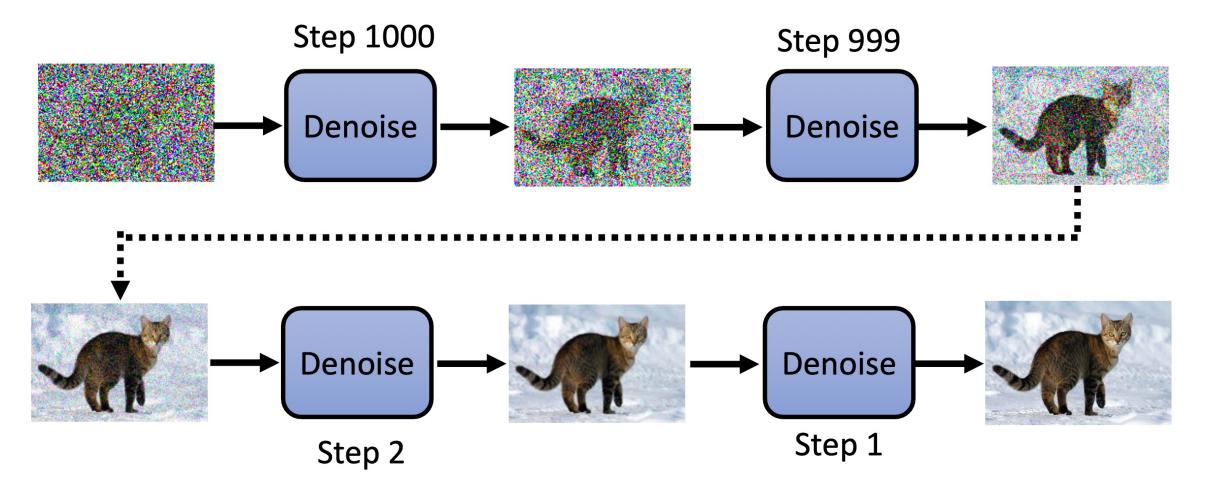
DIFFUSION MODEL

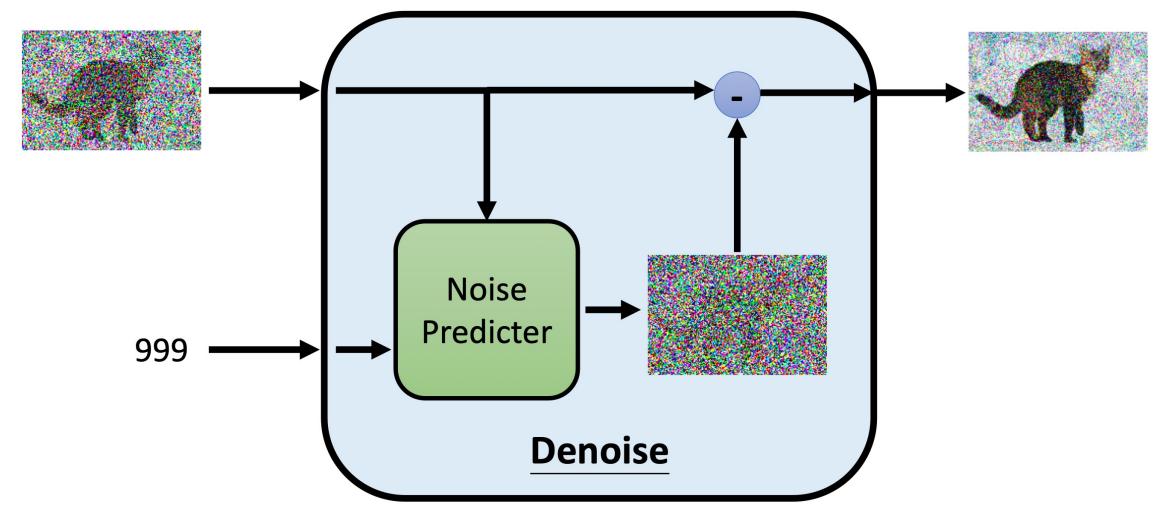
Denoising diffusion probabilistic models

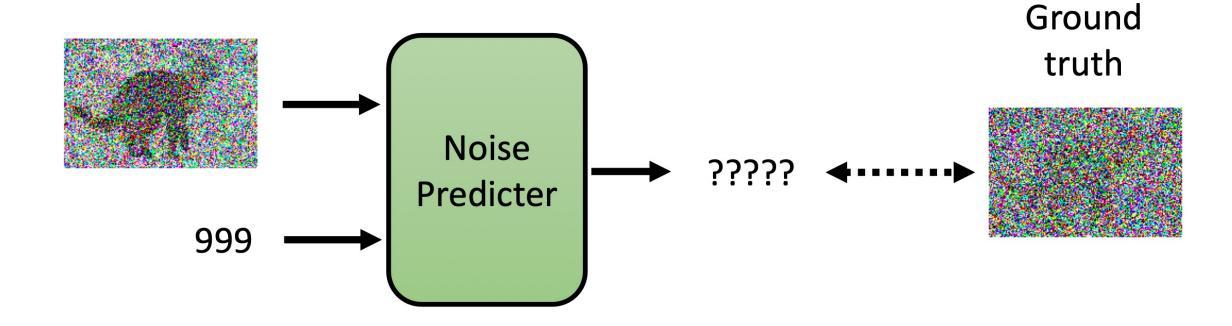
J Ho, A Jain, P Abbeel - Advances in neural information ..., 2020 - proceedings.neurips.cc

... This paper presents progress in **diffusion probabilistic models** [53]. A **diffusion probabilistic model** (which we will call a "**diffusion model**" for brevity) is a parameterized Markov chain ...

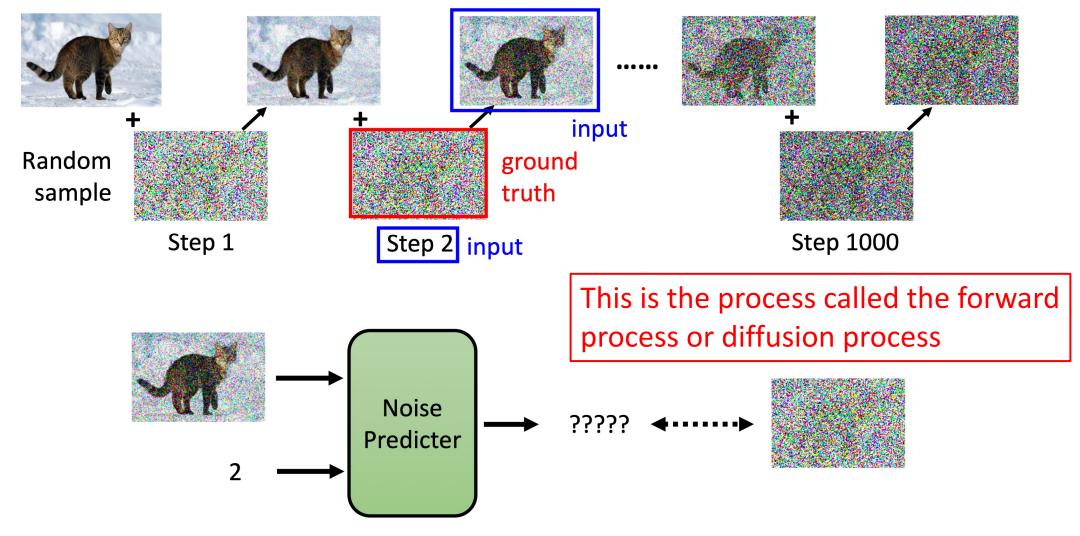
☆ Save 夘 Cite Cited by 4825 Related articles All 6 versions ১৯

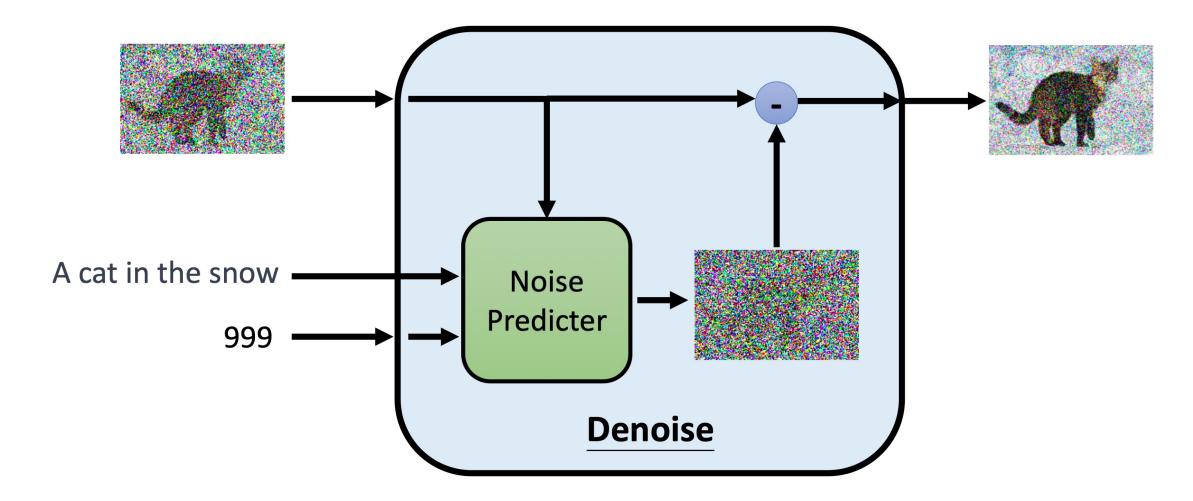














Algorithm 1 Training

1: repeat

2: $\mathbf{x}_0 \sim q(\mathbf{x}_0)$

3: $t \sim \text{Uniform}(\{1, \dots, T\})$

4: $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

5: Take gradient descent step on

$$\nabla_{\theta} \left\| \boldsymbol{\epsilon} - \boldsymbol{\epsilon}_{\theta} (\sqrt{\bar{lpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{lpha}_t} \boldsymbol{\epsilon}, t) \right\|^2$$

6: until converged

Ground truth noise

Denoise model

Algorithm 2 Sampling

1: $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

2: **for** t = T, ..., 1 **do**

3: $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ if t > 1, else $\mathbf{z} = \mathbf{0}$

4:
$$\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left(\mathbf{x}_t - \frac{1-\alpha_t}{\sqrt{1-\bar{\alpha}_t}} \boldsymbol{\epsilon}_{\theta}(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$$

5: end for

6: return \mathbf{x}_0

Subtract

predicted noise

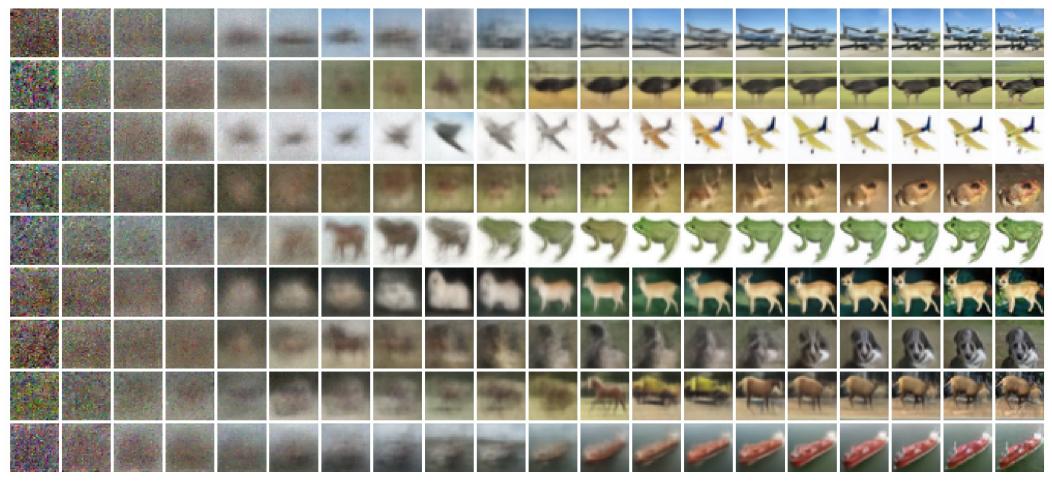
Denoise model



Add ground

truth noise





Unconditional CIFAR10 progressive generation

Diffusion Model

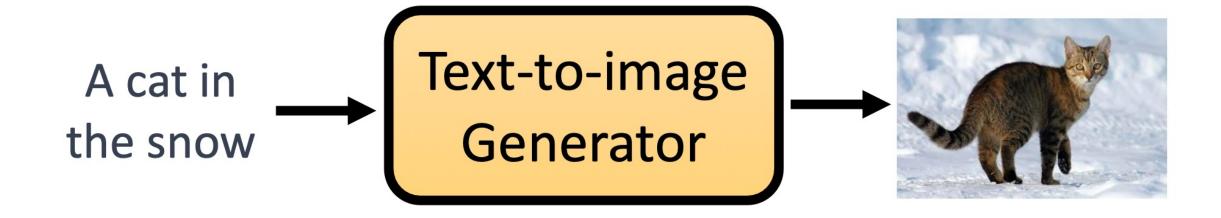


Latent \mathbf{x}_{750}

Decodings $\mathbf{x}_0 \sim p_{\theta}(\mathbf{x}_0|\mathbf{x}_{750})$

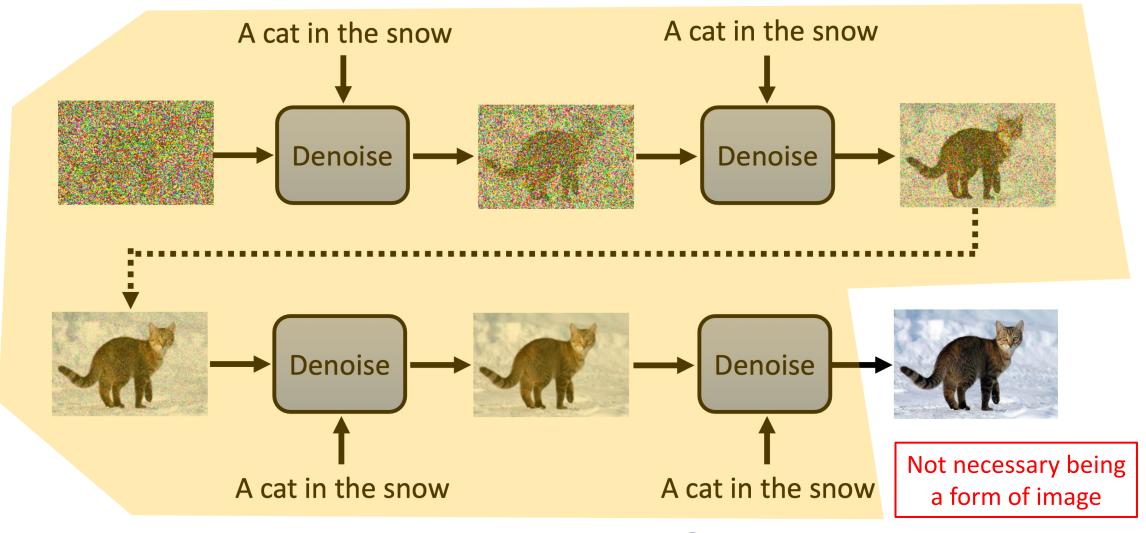
Diffusion Model

How can we generate desired image?





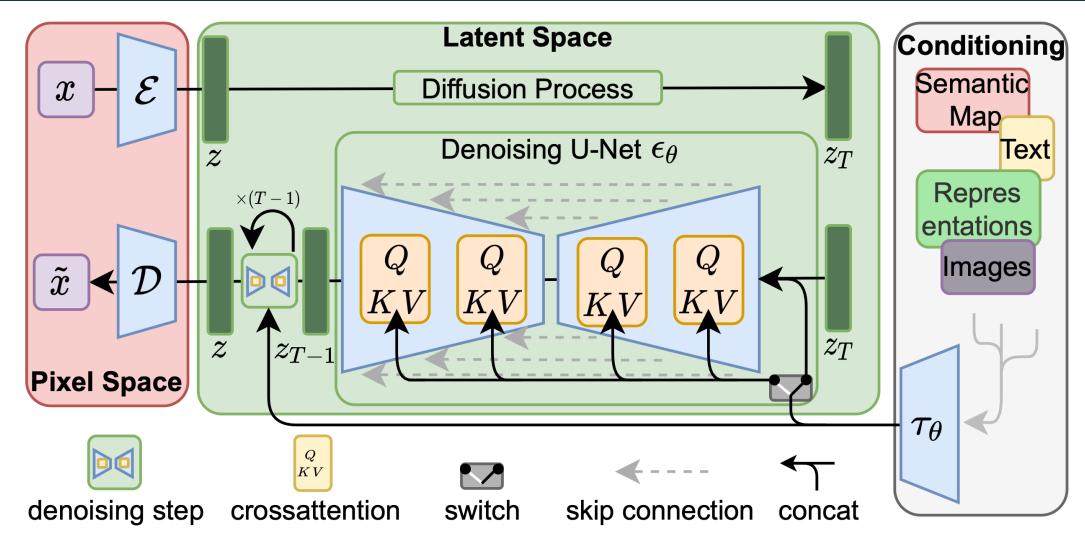
Diffusion Model



High-resolution image synthesis with latent diffusion models **Latent Diffusion** R Rombach, A Blattmann, D Lorenz... - Proceedings of the ..., 2022 - openaccess.thecvf.com ... To lower the computational demands of training diffusion models towards high-resolution image synthesis, we observe that although diffusion models allow to ignore perceptually ... ☆ Save ☑ Cite Cited by 3600 Related articles All 8 versions ♦ **Text Text** A cat in representation the snow **Encoder** Generation Noise latent Model vector **Denoise latent** Decoder vector











Layout-to-image synthesis on COCO

"A street sign that reads
'Latent Diffusion'

"An oil painting of a space shuttle"



Text-to-image *LDM* model for user-defined text prompts







Semantic synthesis of landscape images







ImageNet 64→256 super-resolution







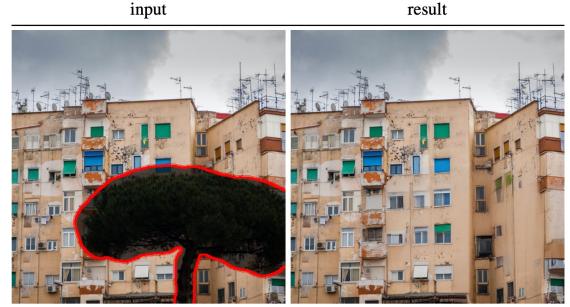
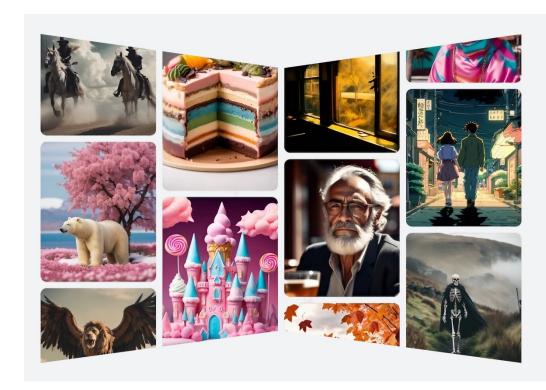


Image inpainting with latent diffusion



Stable Diffusion

Stable diffusion is developed by researchers from the CompVis Group at Ludwig Maximilian University of Munich and Runway with a compute donation by Stability AI and training data from non-profit organizations.



Stable Diffusion

Get involved with the fastest growing open software project. Download and join other developers in creating incredible applications with Stable Diffusion as a foundation model.

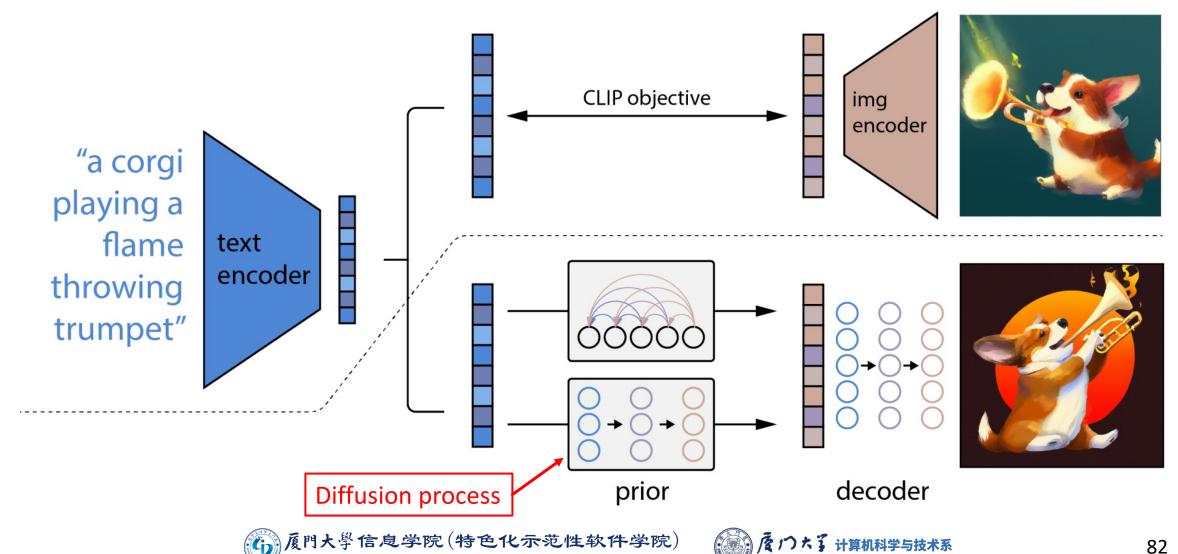
Try Stable Diffusion

Download Code

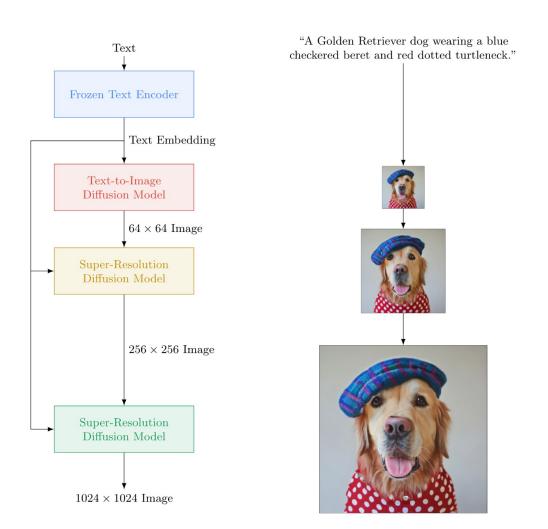




DALL-E



Imagen









Sprouts in the shape of text 'Imagen' coming out of a A photo of a Shiba Inu dog with a backpack riding a A high contrast portrait of a very happy fuzzy panda fairytale book.

Bike. It is wearing sunglasses and a beach hat.

There is a painting of flowers on the wall behind him.









A cute sloth holding a small treasure chest. A bright golden glow is coming from the chest.



A brain riding a rocketship heading towards the moon. A dragon fruit wearing karate belt in the snow.





A strawberry mug filled with white sesame seeds. The mug is floating in a dark chocolate sea.





Midjourney



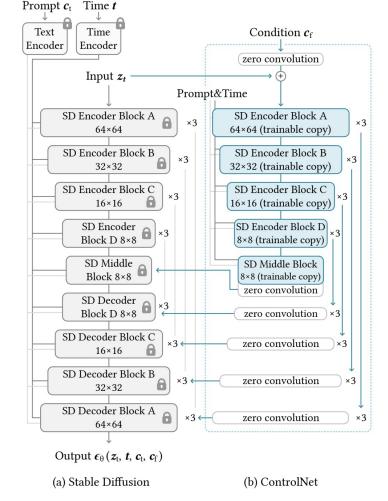
These fake images of the Pope and Donald Trump have gone viral in recent weeks, both were created on Midjourney v5.

ControlNet

Adding conditional control to text-to-image diffusion models

- L Zhang, <u>A Rao, M Agrawala</u> Proceedings of the IEEE/CVF ..., 2023 openaccess.thecvf.com
- ... Learning **conditional controls** for large text-to-image diffusion ... network architecture that learns **conditional controls** for large ... for learning diverse **conditional controls**. The trainable copy ...
- ☆ Save ⑰ Cite Cited by 440 Related articles All 3 versions ≫
- A new concept called zero convolution layers, with weights initialized to zeros so that they progressively grow during the training.
- This architecture ensures that harmful noise is not added to the deep features of the large diffusion model.









Conclusion

After this lecture, you should know:

- What is a generative model?
- How generator and discriminator improve each other?
- How does transposed convolution work?
- How to design application specific loss to train with adversarial loss?
- What is the main principle of diffusion model?



Suggested Reading

- Adversarial Nets Papers
- Tips and tricks to make GANs work
- 令人拍案叫绝的Wasserstein GAN
- ■李宏毅讲Diffusion Model



Assignment 4

Assignment 4 is released. The deadline is 18:00, 2nd December.



Thank you!

- Any question?
- ■Don't hesitate to send email to me for asking questions and discussion. ©

